PARKER J KNOPF | parker.knopf@gmail.com

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CAREER OBJECTIVE

Dedicated to leveraging proven experience with academic success to contribute to company goals. An unparalleled tenacity since childhood to immerse myself within the field in aspiration to further technological innovation!

EDUCATION

MECHANICAL ENGINEERING, MS | (Controls and Mechatronics)

MECHANICAL ENGINEERING, BS | GPA: 3.87 (Cum-laude)

UNIVERSITY OF CALIFORNIA, SAN DIEGO

- **Relevant Coursework:** Signals and Systems, Statics and Dynamics, Mathematical Computation, Programing, Thermodynamics, Material Science, Fluid Dynamics, Solid Mechanics
- Clubs: Triton Robotics (Engineer Lead), Human Powered Submarine, Men's Club Water Polo (President)

EXPERIENCE

HOLOGIC | R&D (Mechanical and Systems) Engineer - Intern

Precision Instrument System Engineering Project

- Developed from scratch a precision ultrasonic embedded system instrument to characterize tube height, relieving the duty of a full-time engineer to conduct root cause analysis of an instrument defect
- Trusted with autonomy to select electronic components, develop mechanical design, and program software

Prototype Development of Next Generation Product

- Integrated electronic modules into a self designed and assembled functional first-generation prototype
- Showcased to marketing team and other stakeholders, receiving positive feedback on prototype •
- Conducted multidisciplinary tasks including software development, hardware integration, and iterative product development based on gathered feedback from external workflow operations

MORIMOTO'S LAB | Mechanical Engineer - Researcher

UCSD Soft Robotics Research Lab

- Prototyped and developed an innovative non-invasive endovascular surgical device in collaboration with a small team of student researchers under the guidance of Professor Morimoto.
- Evaluated feasibility through clinical trials, lab experimentation, literature research, and FEA •
- Participated in clinical collaborator meetings to aid in product development and clinical adoption •

VALITUS TECHNOLOGIES | Mechanical Engineer - Intern

Product Development for Start-up Corporation

- Contributed to design on Critical AI Security Project for the USAF (United States Air Force)
- Independently modified, and added final CAD geometry in preparation for mass production injection molding •
- Quickly adapted to company workflow and using foreign file layouts created by international partners •

TECHNICAL ENGINEERING PROJECTS

WEARABLE HAPTIC ARM Obstacle Avoidance During Teleoperation (paper)	Fall 2023 60+ hours
REVERSE OSMOSIS TESTING RIG SDP Sponsored by OceanWell (portfolio link)	Spring 2023 200+ hours
AUTONOMOUS SELF-DRIVING CAR Ros2/Python Driven Vehicle (github)	Winter 2022 80+ hours
6DOF ROBOTIC ARM Inverse Kinematics Robotic Arm (portfolio link)	2020 - 2021 150+ hours
3D PCB LIGHT CUBE 216 LED 3D Cube Light Display (portfolio link)	2020 - 2021 100+ hours
HEXAPOD ROBOT 6 Legged 3D Printed Robot (portfolio link)	2017 - 2019 200+ hours

SKILLS

Solidworks DipTrace Python/Java/C++ Autocad Mastercam Embedded Systems

MATLAB Ros2 OpenCV

AWARDS

SkillsUSA National Champion in Auto-Manufacturing Tech. Comp. 1st Place UCSD Robotic Comp.

CERTIFICATIONS

Solidworks Mechanical Design Professional (CSWP) Nvidia DLI Certificate

June 2022 - September 2022

December 2022 - September 2023

April 2019 - September 2020

500+ hours

Graduation: June 2024

300+ hours

100+ hours

2019 - 2023